

Symmetry Breaking and Superfluid Phases of Liquid ^3He from Landau-Ginzburg Theory

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In this paper, we will briefly introduce the application of Landau-Ginzburg (L-G) theory and symmetry breaking in superfluid phases of liquid ^3He . From the solutions of L-G equation for B and A phase, we can identify the symmetry breaking in these two phases. Then we will briefly introduce the physical consequence of the broken relative symmetries in these two phases.

INTRODUCTION

Superfluidity of ^3He

A superfluid is a state of matter in which the matter behaves as a fluid with vanishing viscosity. The most famous example is ^4He , an isotope of He. Due to large zero-point motion of the atoms in ^4He , it still in a phase of liquid at absolute zero temperature. Since ^4He has zero nucleus spin, at a temperature of few K, the ensemble of the ^4He atoms forms a quantum Bose liquid. When $T < T_c = 2.2$ K, ^4He Bose-condenses and the correlated motion of the Bose condensate has no dissipation, therefore, it exhibits properties of superfluidity.

^3He also doesn't solidify at absolute zero temperature. It also can become a superfluid. However, ^3He has $1/2$ nucleus spin, therefore, it becomes a quantum Fermi liquid at few K. In order to behave as a superfluid, ^3He atoms must first pair up and form Cooper pairs, which have integer spin. Then the ensemble of such bosonic Cooper pairs will Bose-condenses and results in superfluidity at low temperature.

Not only the complicity in the formation of Cooper pair, there is a more important and interesting consequence of the non-zero nucleus spin, namely, non-trivial internal structure, followed by additional degrees of freedom on low energy scale $E \ll T_c$. The Cooper pair has non-zero spin $S = 1$ and non-zero angular momentum of the orbital motion of the Cooper pair $L = 1$. The strong correlation of the spin and angular momenta of the Bose condensate results in magnetic and liquid-crystal-like ordering, which means not only the gauge symmetry, the $SO(3)_S$ for spin and $SO(3)_L$ for orbital rotation symmetries are also spontaneously broken in ^3He .

Superfluid Phase of ^3He

Since $S = 1$ and $L = 1$ are both three dimensional representation of $SO(3)_S$ and $SO(3)_L$ group respectively. Therefore the parameter space is $\mathbf{3} \otimes \mathbf{3}$, which is nine dimensional. Such large degrees of freedom enrich the classification of the superfluid phases of ^3He . Three of them are under extensive investigation[1]:

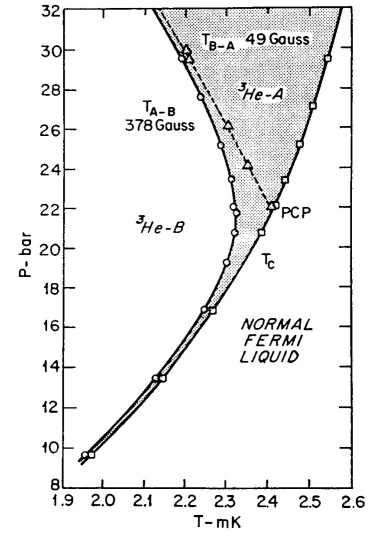


FIG. 1: Phase diagram for ^3He at the lowest magnetic field[2].

- The quasi-isotropic phase $^3\text{He-B}$. The total angular momentum of the Cooper pair is zero, $J = 0$, where $\vec{J} = \vec{L} + \vec{S}$.
- The anisotropic phase $^3\text{He-A}$. In this phase, the Cooper pair in this state has non-zero projection of the orbital angular momentum $m_l = 1$ on some axis \hat{l} , where \hat{l} is not only an axis of spontaneous orbital anisotropy of this liquid, but also represents the direction of its spontaneous ferromagnetic moment. The projection of spin angular momentum is zero $m_s = 0$.
- There is another phase, namely, the $^3\text{He-A}_1$ phase, which only exists if a magnetic field is present. Being different from the $^3\text{He-A}$ phase, it has $m_l = 1$ and also non-vanishing projection of spin angular momentum $m_s = 1$. The quantization axes for spin and orbital angular momentum are not necessarily parallel.

In this next section, we will mostly focus on B and A phase.

SYMMETRY BREAKING IN ^3He SUPERFLUID

If we only consider the interactions involved in the formation of condensed states, then the free energy is invariant under the following transformation

$$G = SO(3)_L \times SO(3)_S \times U(1)_\phi, \quad (0.1)$$

where the two $SO(3)$ groups describe rotations in spin space and orbital space respectively, and $U(1)_\phi$ describes gauge transformation.

Symmetry breaking will result in different phases [3]:

- $G \supset SO(3)_L \times SO(3)_S \rightarrow SO(3)_{L+S}$, where $SO(3)_{L+S}$ describes some linear combinations of transformations from $SO(3)_L$ and $SO(3)_S$ groups. This symmetry breaking results in B phase.
- $G \supset SO(3)_L \times U(1)_\phi \rightarrow U(1)_{L_z+\phi}$, which results in A phase.

In this section, we will first briefly review the Landau-Ginzburg theory and then introduce these two phases in details.

Landau-Ginzburg Theory for Liquid ^3He

The wave function of Cooper pair is

$$\psi = \sum_{m_s, m_l} \mathcal{A}_{m_s, m_l} \psi_{m_s, m_l}, \quad (0.2)$$

where $m_s, m_l = +, 0, -1$ corresponds to the magnetic quantum number for spin and orbital angular momentum $M_S, M_L = 1, 0, -1$ respectively.

We can write the L-G functional in terms of a 3×3 matrix $A_{\alpha i}$, defined as $A_{\alpha i} = \sum_{m_s, m_l} \mathcal{A}_{m_s, m_l} \lambda_\alpha^{m_s} \lambda_i^{m_l}$, where $\lambda_\alpha^0 = \hat{z}_\alpha, \lambda_\alpha^\pm = (\hat{x}_\alpha \pm i\hat{y}_\alpha)/\sqrt{2}$. Then The behavior near the critical temperature T_c is described by the quadratic term in the L-G functional $F_{LG} \supset (T - T_c) A_{\alpha i}^* A_{\alpha i}$, and the equilibrium order parameter $A_{\alpha i}^0$ can be found by solving G-L equations

$$\frac{\delta F_{\text{bulk}}^{LG}[A_{\alpha i}]}{\delta A_{\alpha i}} = 0, \quad (0.3)$$

where $F_{\text{bulk}}^{GL} \subset F_{LG}$ is the bulk condensation energy term in the L-G free energy functional[4].

By this method, we can find the order parameter for B and A phase:

- When the pressure below the so called polycritical point, the solution of the L-G equation is

$$A_{\alpha i}^0 = \Delta_B(T, P) \delta_{\alpha i}. \quad (0.4)$$

In terms of the amplitude, we have

$$\mathcal{A}_{+,-} = \mathcal{A}_{-,+} = \mathcal{A}_{0,0} = \Delta_B(T, P). \quad (0.5)$$

Therefore, the projection of the total angular momentum $m_j = m_s + m_l = 0$, and the state is isotropic, which indicates $J = 0$.

- When the pressure above the polycritical point, we obtain the A phase solution [1]:

$$A_{\alpha i}^0 = \Delta_A(T, P) \hat{z}_\alpha (\hat{x}_i + i\hat{y}_i). \quad (0.6)$$

In term of the amplitude, we have only one non-zero order parameter:

$$\mathcal{A}_{0,+} = \sqrt{2} \Delta_A(T, P), \quad (0.7)$$

from which we can tell the state has $m_s = 0$ and $m_l = 1$. The quantization axes for spin and orbital angular momentum are both along the same axis.

Manifold of the Degenerate State and Residue Symmetry

The transformation of the total group $g \in G$ can be described explicitly as

$$(gA^0)_{\alpha i} = e^{i\phi} R_{\alpha\beta}^S A_{\beta j} R_{ji}^L, \quad (0.8)$$

where R^S, R^L are the matrices of rotations $SO(3)_S, SO(3)_L$ in the orbital and spin spaces respectively, ϕ is the parameter of the global gauge transformation $U(1)$. Applying this to different state Eq.(0.4) and Eq.(0.6), we obtain[1]

$$\text{B phase: } A_{\alpha i}^0 = \Delta_B(T, P) e^{i\phi} R_{\alpha i} \quad (0.9)$$

$$\text{A phase: } A_{\alpha i}^0 = \Delta_A(T, P) \hat{s}_\alpha (\hat{e}_i^{(x)} + \hat{e}_i^{(y)}), \quad (0.10)$$

where \hat{s}_α is the spin axis and $\hat{e}^{(x)} \times \hat{e}^{(y)} = \hat{l}$ is the deribein. \hat{l} is the orbital axis.

From these two general forms, we can obtain the manifolds and residue symmetries for the degenerate states:

- B phase: B phase is described by 1) ϕ parameter, and 2) the orthogonal real matrix $R_{\alpha i}$. The space corresponding to $U(1)$ is just S^1 . As for $R_{\alpha i}$, notice it's from $R_{\alpha i} = R_{\alpha\beta}^S \delta_{\beta j} (R^L)_{ij}^{-1}$ and $\delta_{\beta j}$ is from the initial solution Eq.(0.4), $R_{\alpha i}$ describes the relative rotation of spin and orbital frames. When this apply to the initial state with $J = 0$, the total angular momentum of resulting state is no longer zero. Therefore, the manifold of the equilibrium degenerate states R_B is [1]

$$R_B = S^1 \times SO(3)_{rel}, \quad \dim(R_B) = 4. \quad (0.11)$$

where S^1 is described by the phase ϕ and $SO(3)_{rel}$ is for the relative spin-to-orbit rotations $R_{\alpha i}$.

Because $R_{rel} = R^S (R^L)^{-1}$, it's invariant under a spin rotation R^S accompanied by an equal rotation R^L of the orbital space. Therefore, the residue

symmetry is $H = SO(3)_J$, the group of combined rotations. As a result, the manifold R_B is just the coset space $R_B = G/H$.

- A phase: The general form of the solution Eq.(0.10) has the following symmetries:
 1. Spin rotation $SO(2)_S$ about axis \hat{s} ;
 2. $U(1)_c$: $U(1)$ gauge transformation $e^{i\phi}$, accompanied by orbital rotation of the dreibein $\hat{e}^{(x)}, \hat{e}^{(y)}$ and \hat{l} about the axis \hat{l} by the same angle ϕ , since under such a rotation $\hat{e}^{(x)} + i\hat{e}^{(y)} \rightarrow e^{-i\phi}(\hat{e}^{(x)} + i\hat{e}^{(y)})$, where the factor $e^{-i\phi}$ is cancelled out by the $U(1)$ transformation;
 3. A discrete combined symmetry Z_2^c , the spin rotation of \hat{d} by angle π about a perpendicular axis, accompanied by gauge transformation $e^{i\pi}$. The former flips the sign which is further cancelled out by the latter $e^{i\pi}$.

Therefore, the residue symmetry is $H = SO(2)_S \times U(1)_c \times Z_2^c$, and the manifold of the equilibrium degenerate state is [1]

$$R_A = G/H = S^1 \times SO(3)_{rel}/Z_2. \quad (0.12)$$

Be aware that here the $SO(3)_{rel}$ describes the rotations about the axis $\hat{l} = \hat{e}^{(x)} \times \hat{e}^{(y)}$ relative to gauge transformations, which is different from the one in B phase.

PHYSICAL RESULTS FROM THE BROKEN RELATIVE SYMMETRIES

Notice that both B and A phase have broken relative symmetries, summarized as follows:

- B phase: Relative spin-orbital rotation: Only the relative rotation of spin and orbital frame will change the degenerate state.
- A phase: Relative gauge-orbital rotation: Only the gauge transformation counted from the orbital rotations around \hat{l} will change the degenerate state.

Such broken relative symmetries have very interesting physical consequence.

For B phase, the spin or orbital space are both isotropic. However, the broken spin-orbital rotational symmetry results in relative anisotropy of the magnetic and orbital properties in an isotropic liquid. If an anisotropy axis \hat{n}_l of orbital properties is induced by external conditions, then an anisotropy axis relative to the orbital axis $\hat{n}_s = R_{\alpha i} \hat{n}_l$ of the magnetic properties will simultaneously appear.

For A phase, due to the breaking gauge-orbital rotational symmetry, all the gauge invariant quantities in A phase will obtain an anisotropy axis \hat{l} . They are invariant under rotations around such an axis \hat{l} .

SUMMARY

In this paper, we briefly introduced the symmetry breaking of ${}^3\text{He}$ and the resulting B and A phase. The new features, broken relative symmetries, generate many interesting physical properties of the superfluid ${}^3\text{He}$.

There are also many other important and intriguing aspects in the study of superfluid ${}^3\text{He}$. For example, in the topological perspective, topological defects are under extensive investigation; ${}^3\text{He}$ vortices also have lots of fascinating content to be studied. In addition, superfluid phases can also be studied with the help of gravity theory, which I found very attractive.

Acknowledgements

Here I would like to express my sincere gratitude to Prof. McGreevy. He provided me with lots of help when I was writing this paper.

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