

What's a virtual particle? (continued)

$$T = V + \underbrace{V \pi V}_1 + V \pi V \pi V + \dots$$

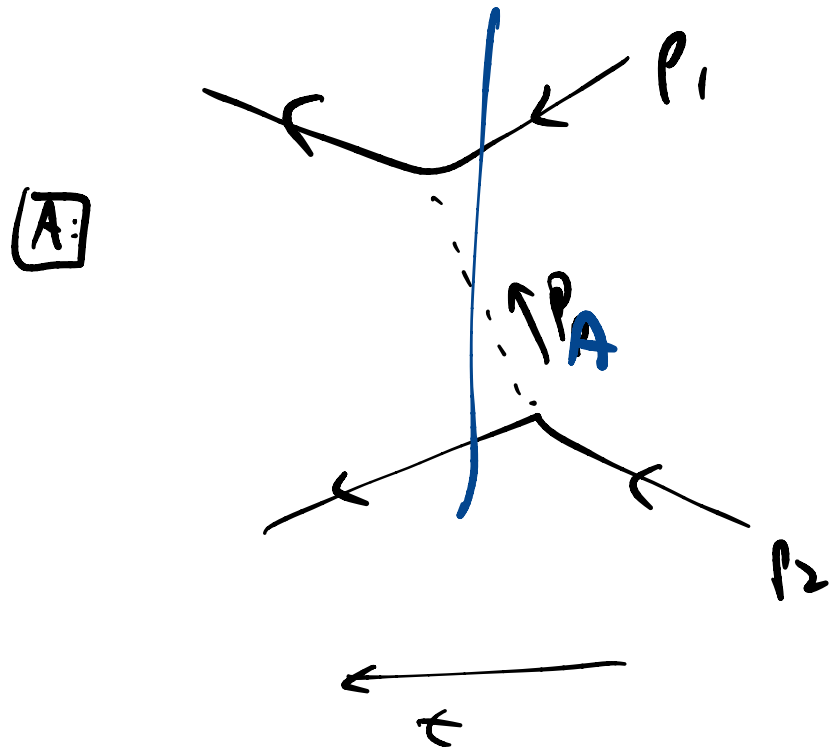
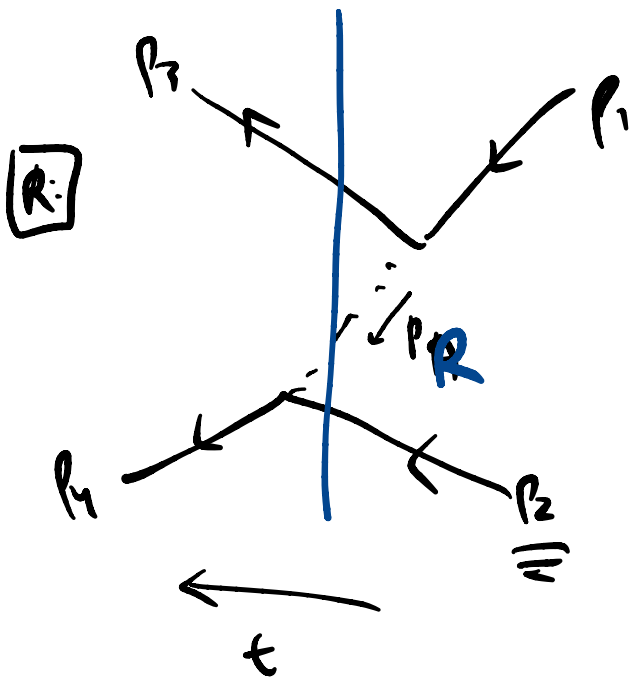
$$\pi = \frac{1}{E - H_0 + i\epsilon}$$

eg: $V = g \int d^d x \Phi^*(x) \Phi(x) \phi(x)$

$|i\rangle = |\vec{p}_1, \vec{p}_2\rangle$ 2 nucleons

$|f\rangle = |\vec{p}_3, \vec{p}_4\rangle$ " "

$$T_{if} = \sum_{n=R,A} V_{fn} \frac{1}{E_i - E_n + i\epsilon} V_{ni} + \dots$$



$$|R\rangle = |p^3, p_\phi, p^2\rangle \quad |A\rangle = |p^4, p_\phi, p_1\rangle$$

$$V_{ni}^R = \langle R | V | \vec{p}_1, \vec{p}_2 \rangle$$

$$= \langle p^3, p_\phi | V | p_1 \rangle \langle p_2 | p_2 \rangle$$

$$= g \int d^d x \underbrace{\langle p_\phi | \phi(x) | 0 \rangle}_{e^{-i\vec{p}_\phi \cdot \vec{x}}} \underbrace{\langle p^3 | \Phi^\dagger \Phi | p^1 \rangle}_{e^{-i(\vec{p}_3 - \vec{p}_1) \cdot x}}$$

$$= g \delta^d(\vec{p}_1 - \vec{p}_3 - \vec{p}_\phi)$$

$$\Rightarrow T_{fi} = \sum_{n=R,A} \int d^d p_\phi \delta^d(p_1 - p_3 - p_\phi) \delta^d(p_2 - p_4 - p_\phi) \frac{g^2}{E_i - E_{n^{\text{tic}}}}$$

on-shell ϕ particles:

$$E_\phi = \sqrt{|\vec{p}_\phi|^2 + m_\phi^2}$$

$$E_{n=R} = E_3 + E_\phi^R + E_2 = E_3 + \sqrt{|\vec{p}_1 - \vec{p}_3|^2 + m_\phi^2} + E_2$$

$$\Rightarrow E_i - E_{n=R} = E_1 - E_3 - E_\phi^R = -\Delta E - E_\phi$$

$$\Delta E \equiv E_1 - E_3 = E_2 - E_4$$

$$\underline{1.} \quad \vec{p}_\phi = p_2 - p_4 = p_3 - p_1$$

$$\Rightarrow E_\phi^A = \sqrt{|p_1 - p_3|^2 + m_\phi^2} = \sqrt{|p_2 - p_4|^2 + m_\phi^2} = E_\phi^R = E_\phi.$$

$$\Rightarrow E_i - E_{n=A} = +\Delta E - E_\phi$$

$$\rightarrow \sum_{n=R, A} \frac{g^2}{E_i - E_n} = \frac{g^2}{-\Delta E - E_\phi} + \frac{g^2}{+\Delta E - E_\phi}$$

$$= 2E_\phi \frac{g^2}{\Delta E^2 - E_\phi^2} = 2E_\phi \cdot \frac{g^2}{\underbrace{k^2 - m_\phi^2 + i\epsilon}}$$

$$k^\mu = p_1^\mu - p_3^\mu = (\Delta E, \vec{p}_\phi)^\mu.$$

$$k^2 = (\Delta E)^2 - p_\phi^2 \neq m_\phi^2.$$

4.9 Observables from G_R

$$G_{AB}^R(x) = -i \theta(t) \langle [A(t, \vec{x}), B(0, \vec{0})] \rangle.$$

consider: ^{perturb.} $\delta H(t) = \int d^d x f(t, \vec{x}) B(\vec{x})$

↑
we pick.

Let ρ_0 be some nice state.

eg: $\rho_0 = \frac{e^{-\beta H_0}}{Z} \xrightarrow{\beta \rightarrow \infty} |0\rangle\langle 0|$

↑
g.s. of H_0 .

observe:

$$\rho(t) = U(t) \rho_0 U(t)^\dagger$$

$$\langle A(\vec{x}) \rangle(t) = \text{tr} \rho(t) A(\vec{x})$$

$$= \text{tr} \rho_0 \underline{U^\dagger(t)} A(\vec{x}) U(t)$$

$$= \text{tr} \rho_0 U_I^\dagger \underline{A(\vec{x}, t)} U_I(t)$$

interaction picture:

$$\left\{ \begin{array}{l} U_I(t) = \mathcal{T} e^{-i \int^t \delta H(t') dt'} \\ A(\vec{x}, t) = e^{i H_0 t} A e^{-i H_0 t} \end{array} \right.$$

Linear Response: assume f small.

$$\begin{aligned}
 f(A)(t, \vec{x}) &= -i \text{tr} \rho_0 \int dt' [A(t, \vec{x}), \delta H(t')] \\
 &= -i \int d^D x' \langle [A(t, \vec{x}), B(t', \vec{x}')] \rangle f(t', \vec{x}') \\
 &= -i \int_{-\infty}^{\infty} d^D x' \theta(t-t') \langle [A(x), B(x')] \rangle f(x') \\
 &= \int d^D x' G_{AB}^R(x, x') f(x').
 \end{aligned}$$

$$\left[f(A)(\omega, \vec{k}) = \underbrace{G_{AB}^R(\omega, \vec{k})}_{\text{"susceptibility"}} \cdot f(\omega, \vec{k}) \right]$$

suppose conserved charge.

$$\underline{g}: \underline{\partial}_\mu(x).$$

$$\begin{aligned}
 E_x &= i\omega A_x \quad (A_0 = 0) \\
 \delta H &= A_x J^x \quad \text{i.e. } \begin{cases} \hat{B} = J_x \\ \hat{f} = A_x \end{cases}
 \end{aligned}$$

5 Spinor fields & fermions

5.1 Lightning summary of group theory.

Group: $G = \{g_i\}$

s.t. ① $g_1, g_2 \in G$

② $(g_1, g_2)g_3 = g_1(g_2, g_3) \in G$

③ $\exists g_0$ s.t. $g_0 g_i = g_i \quad \forall g_i$

④ $\forall i \exists g_i^{-1}$ s.t. $g_i g_i^{-1} = g_0$
 $= g_i^{-1} g_i$

If $g_i g_j = g_j g_i \quad \forall i, j$
 G is abelian.

order of G $|G| \equiv \#$ elements.

A Lie group has elts labelled by continuous parameters.

ie. a Lie group $G = \{g(\theta_1, \dots, \theta_n)\}$

$n = \dim G = \# \text{ of coords.}$

$|G| = \infty.$

A Representation R of G

is a map $G \rightarrow$ linear ops on some \mathcal{H}

$g \mapsto \hat{D}_R(g) : \mathcal{H} \rightarrow \mathcal{H}$

respecting the group law (a homomorphism)

$$\hat{D}_R(g_1) \hat{D}_R(g_2) \stackrel{\downarrow}{=} \hat{D}_R(g_1 g_2)$$

IF:
 $\exists S$ s.t.

$$e^{i\phi(g_1, g_2)}$$

"projective
represent."

Regard $R \simeq R'$ if $\exists D_R(g) = S^{-1} D_{R'}(g) S$

R is reducible if $D_R \simeq \left(\begin{array}{c|c|c} D_{R_1} & 0 & \\ \hline 0 & D_{R_2} & \\ \hline & & \dots \end{array} \right)^{\forall g}$

$$R \simeq R_1 \oplus R_2 \oplus \dots$$

$$\dim R \equiv \dim \mathcal{H}.$$

Lie algebra: Let $g(\theta_a=0)$ be the identity

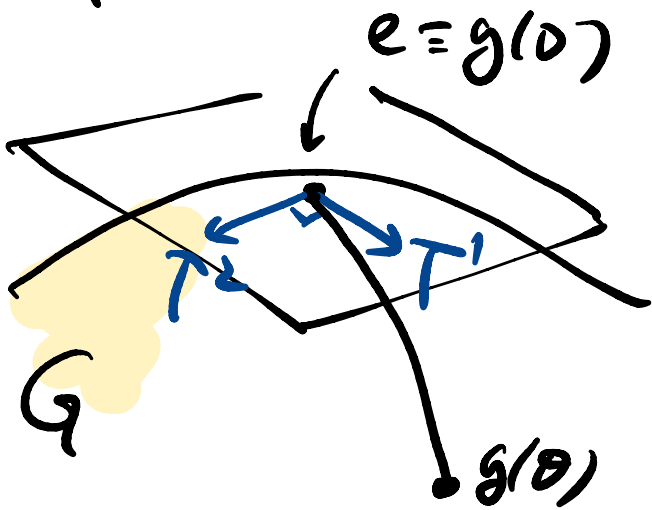
$$D_R(g(\theta_a=0)) = \mathbb{1} + i \theta_a T_R^a + \mathcal{O}(\theta^2)$$

$$\underline{T_R^a} \equiv -i \partial_{\theta_a} D_R(g(\theta)) \Big|_{\theta=0}.$$

generators of G
in rep R .

$$D_R(g(\theta)) \stackrel{\cong \mathfrak{su}(2)}{=} e^{-i \theta_a T_R^a}$$

(is unitary if $T = T^\dagger$)



$$D_R(g_1) \cdot D_R(g_2) \stackrel{\text{def of } R}{=} D_R(g_1 g_2) \stackrel{\exists \theta^3_{\text{st.}}}{=} e^{-i \theta_a^3 T_R^a}$$

θ 's small: $\theta^3_a = \theta^1_a + \theta^2_a - \frac{1}{2} \theta^1_b \theta^2_b f^ab_c + O(\theta)^3$

f^ab_c defined by

$$[T^a, T^b] = i f^ab_c T^c$$

(Lie algebra.)

Structure constants } same for every R .

Convention: $\text{tr } T^a T^b = \frac{1}{2} f^ab_c$

Lie algebra

Lie group

G_0

\sim

$\exp(\mathfrak{g})$

\uparrow

Component of G contains $\mathbb{1}$.

Casimir \equiv op that commutes w generators
 $\propto \mathbb{1}$ on an irreducible rep
 \equiv irrep.

\mathfrak{g} : rotation group in 3d.

generators of rotation about x, y, z axes

$J^{x,y,z}$ satisfy $(i,j,k = x,y,z)$

$$[J^i, J^j] = i \epsilon^{ijk} J^k \quad \leftarrow \begin{matrix} \mathfrak{so}(3) \\ = \mathfrak{su}(2) \end{matrix}$$

$$f_{jk}^{ij} = \epsilon^{ijk} f_{jk}$$

A Casimir is $J^2 \equiv \sum_i (J^i)^2$

$$[J^2, J^i] = 0 \quad \forall i.$$

$J^2 = j(j+1) \mathbb{1}$ on the $\mathfrak{su}(j)$ rep.

$$\dim R_j = 2j+1.$$

A finite rot. $\sim \mathcal{H}_j$

$$D(\hat{n}, \theta) = e^{-i\theta \hat{n} \cdot \mathbf{J}}$$

3 parameters
 $\hat{n} \cdot \hat{n} = 1$
 $\dim SO(3)$
 $> \dim SU(2) = 3$

y: j=1: $(\mathcal{J}_{j=1}^i)_{jk} = i \in^{ijk}$

y: $(\mathcal{J}_{j=1}^3) = i \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$

j=1/2: $(\mathcal{J}_{j=1/2}^i) = \frac{1}{2} \sigma^i$

j=0: $(\mathcal{J}_{j=0}^i) = 0$

i.o. $e^{i\theta \mathcal{J}_{j=0}} = \mathbb{1}$

spin $j \in \mathbb{Z} + \frac{1}{2}$: $(\mathcal{J}^3)_{mm'} = \delta_{mm'} m$ $(\mathcal{J}^{\pm})_{mm'} = (\mathcal{J}^1 \pm i\mathcal{J}^2)_{mm'}$
 $m, m' \in \{-j, -j+1, \dots, j-1, j\}$ $= \delta_{m', m \pm 1} \sqrt{(j \mp m)(j \pm m + 1)}$

$$\textcircled{*} [J^i, J^j] = i \epsilon^{ijk} J^k \equiv \text{" } J \text{ is a vector"}$$

$$14 \rightarrow D_R(14)$$

$$\Rightarrow \mathcal{O} \rightarrow D_R \cup D_R^\dagger.$$

$$\underline{\text{i.e.}}: D_{(j=1)}(g)^k_j J^j = D_R(g) J^k D_R(g)^\dagger.$$

inf' of this is $\textcircled{*}$

$$[J^i, K^j] = i \epsilon^{ijk} K^j \equiv \text{" } K \text{ is a vector"}$$

General d: let $J^i \equiv \epsilon^{ijk} \underbrace{J^{jk}}_{\text{rot in } jk \text{ plane}}$
 \uparrow
 rot about i

$$[J^{ij}, J^{kl}] = i \left(\delta^{jk} J^{il} + \delta^{il} J^{jk} - \delta^{ik} J^{jl} - \delta^{jl} J^{ik} \right).$$

$\mathfrak{so}(d)$

$$\left(J_{(j=1)}^{ij} \right)_e^k = i \left(\delta^{ik} \delta_e^j - \delta^{jk} \delta_e^i \right).$$

$$J_{(j=1/2)}^{ij} = \epsilon^{ijkl} \frac{1}{2} \sigma^k = \frac{i}{4} [\sigma^i, \sigma^j].$$

for general d : given d matrices $k \times k$
satisfying $\{ \sigma^i, \sigma^j \} = 2 \delta^{ij}$

we can make $J^{ij} = \frac{i}{4} [\sigma^i, \sigma^j]$
satisfying $\mathfrak{so}(d)$

Define the Lie group

$$O(d) \equiv \left\{ \begin{array}{l} d \times d \text{ real matrices } O_i \text{ s.t.} \\ |O_n| = |n| \end{array} \right\}$$

$$\left\{ \begin{array}{l} |n| \equiv n_i n_j \delta^{ij} \\ O_n \equiv O_i^j n_j \end{array} \right.$$

ie. $O^t O = \mathbb{1}$

ie. $(O^t)_i^j \delta_{jk} O^k_l = \delta_{il}$.

$$O = e^{-i \theta^{ij} J^{ij}}$$

$$O^t O = \mathbb{1} \Rightarrow 1 = \det O^t O = (\det O)^2$$

$$\det O = \pm 1.$$

$\Rightarrow O(d)$ has 2 components

$$= SO(d) \cup \underline{P \cdot SO(d)}$$

$$\uparrow$$

$$\det O = 1$$

$$P = \begin{pmatrix} -1 & & \\ & 1 & \\ & & \ddots \end{pmatrix}$$

'parity'.

$\Rightarrow O$ is real, $O^t = O^{-1}$

$\Rightarrow J^{ij}$ is antisymmetric & imaginary.

there are $\frac{d(d-1)}{2}$ of them.

a basis $(J_{(j=1)}^{ij})^k$.

$$(J_{(j=1)}^{ij})^k = i (\delta^{ik} \delta_e^j - \delta^{jk} \delta_e^i).$$

$y \quad d=2 \quad SO(2) :$

$$T = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \sigma^2$$

$$e^{i\beta T} = \mathbb{1} \cos\beta + i\sigma^2 \sin\beta$$

$$\uparrow \\ T^2 = \mathbb{1}$$

$$= \begin{pmatrix} \cos\beta & \sin\beta \\ -\sin\beta & \cos\beta \end{pmatrix}$$

$$\underline{\underline{D_{j=\frac{1}{2}}(\hat{n}=\hat{z}, \theta)}} = e^{-i\theta\sigma^3} \\ = \mathbb{1} \cos\theta - i\sigma^3 \sin\theta$$

$$= \begin{pmatrix} \cos\theta & -i\sin\theta \\ i\sin\theta & \cos\theta \end{pmatrix}$$

$$= \begin{pmatrix} e^{-i\theta} & 0 \\ 0 & e^{i\theta} \end{pmatrix}$$

$$D_j(g_1, g_2) = D_j(g_1) D_j(g_2)$$

$G \rightarrow$ linear ops

$\mathfrak{g} \mapsto \mathcal{D}(\mathfrak{g})$

$\hat{J} = 0$: $\mathfrak{g} \mapsto \mathbb{1}$.

$$g(\vec{\theta}_1) g(\vec{\theta}_2) = g(\vec{\theta}_3(\vec{\theta}_1, \vec{\theta}_2))$$

↑

$$\left[J^i, J^j \right] = i \epsilon^{ijk} J^k$$

rep of Lie alg.

$$\Rightarrow \mathcal{D}(\mathfrak{g}) = e^{i \hat{h} \cdot \vec{J}}$$

is a rep of Lie group.